## Text Search for 09903733

BRS	Hits	Search Text	D8s	Time Stamp
	1097	(250/359.1 or 250/341.8 or 250/339.11 or 250/559.01).cds.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	586	(162/198 or 162/50).cds.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	752	(342/278 or 342/195).cds.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	103	(356/478).cds.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	2285	(162/198 or 162/50 or 162/263 or 162/dig.10-dig.11 or 162/183 or 162/212 or 162/252 or 162/259 or 162/253 or 162/262 or 162/336 or 162/471 or 162/469).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	42	stationary adj array with sensor	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	9	(stationary adj array with sensor) and paper	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	1023	paper adj manufacturing adj process	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS BRS	3422 1025	kalman adj filter (702/172 or 702/183 or 702/189).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TD8 USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TD8	06/08/04 06/08/04
BRS	1414	(702/97 or 702/104 or 702/155-159 or 702/170).ccis.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	1284	(702/33-34 or 702/36 or 702/40 or 702/81-84).cds.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
	3610	((702/33-34 or 702/36 or 702/40 or 702/81-84).ocls.) or ((702/97 or 702/104 or 702/155-159 or 702/170).ocls.) or ((702/172 or 702/183 or 702/189).ocls.)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
	1134	(702/for.134 or 702/for.135 or 702/for.155 or 702/for.164 or 702/for.172).cds.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04 06/08/04
BRS	1457	(702/for.123-for.124 or 702/for.134 or 702/for.136 or 702/for.141 or 702/for.144-for.148 or 702/for.164 or 702/for.170).ccls.  (702/33 or 702/85 or 702/95 or 702/97 or 702/104 or 702/105 or 702/113 or 702/127 or 702/150 or 702/152 or 702/155 or 702/157-158 or 702/166-167 or	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	
BRS	3604	702/170 or 702/190 or 702/197).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
		((702/for.123-for.124 or 702/for.134 or 702/for.136 or 702/for.141 or 702/for.144-for.148 or 702/for.164 or 702/for.170).cds.) or ((702/33 or 702/36 or 702/35 or 702/95		
BRS	4907	or 702/97 or 702/104 or 702/105 or 702/113 or 702/127 or 702/150 or 702/152 or 702/155 or 702/157-158 or 702/166-167 or 702/170 or 702/190 or 702/197).cds.)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
		(((702/for.123-for.124 or 702/for.134 or 702/for.136 or 702/for.141 or 702/for.144-for.148 or 702/for.164 or 702/for.170).cds.) or ((702/33 or 702/36 or 702/35 or 702/35		
BRS	71	or 702/97 or 702/104 or 702/105 or 702/127 or 702/120 or 702/150 or 702/155 or 702/157-158 or 702/166-167 or 702/170 or 702/190 or 702/190.cds.)) and	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
		(kalman adj filter)		
		((((702/for.123-for.124 or 702/for.134 or 702/for.136 or 702/for.141 or 702/for.144-for.148 or 702/for.164 or 702/for.170).ccls.) or ((702/33 or 702/36 or 702/35 or 702/95		******
BRS	3	or 702/97 or 702/104 or 702/105 or 702/113 or 702/127 or 702/150 or 702/150 or 702/155 or 702/157-158 or 702/166-167 or 702/170 or 702/190 or 702/197).ccls.)) and	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
<del></del>		(kalman adj filter)) and convolution ((((((702/for.123-for.124 or 702/for.134 or 702/for.136 or 702/for.141 or 702/for.148 or 702/for.164 or 702/for.170).ccls.) or ((702/33 or 702/36 or 702/85 or		
BRS	0	702/95 or 702/97 or 702/104 or 702/105 or 702/113 or 702/127 or 702/150 or 702/152 or 702/155 or 702/157-158 or 702/166-167 or 702/170 or 702/190 or	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
		702/197).ccls.)) and (kalman adj filter)) and convolution) and error) and senosr		
900		((((((702/for.123-for.124 or 702/for.134 or 702/for.136 or 702/for.141 or 702/for.144-for.148 or 702/for.164 or 702/for.170).cds.) or ((702/33 or 702/36 or 702/85 or	HERAT: HE ROOHE, EDO. 100. DECIMENT, IDM TOD	06/08/04
BRS	1	702/95 or 702/97 or 702/104 or 702/105 or 702/113 or 702/127 or 702/150 or 702/152 or 702/155 or 702/157-158 or 702/166-167 or 702/170 or 702/190 or 702/197).ccis.)) and (kalman adj filter)) and convolution) and error) and sensor	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	J0/00/04
BRS	125	702/197).ccs.() and (xauman adj inter)) and convolution) and error) and sensor (700/130 or 700/140).cds.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	203	(708/5 or 708/814).cols.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	231	(73/1.45 or 73/1.49 or 73/1.85 or 73/767).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	778 1337	(250/559.19 or 250/559.4).cds. ((700/130 or 700/140).cds.) or ((708/5 or 708/814).cds.) or ((73/1.45 or 73/1.85 or 73/767).cds.) or ((250/559.19 or 250/559.4).cds.)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04 06/08/04
BRS	1337	(((700/130 or 700/140).cds.) or ((708/5 or 708/814).cds.) or ((73/1.45 or 73/1.49 or 73/1.65 or 73/767).cds.) or ((250/559.19 or 250/559.4).cds.)) and (data adj fusion))		
BRS	0	and kalman	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	7580	array adj sensors	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	1	((((700/130 or 700/140).cds.) or ((708/5 or 708/814).cds.) or ((73/1.45 or 73/1.49 or 73/1.85 or 73/767).cds.) or ((250/559.19 or 250/559.4).cds.)) and (data adj fusion))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	56	and filter (array adj sensors) and (kalman adj filter)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
		(((((700/130 or 700/140).cds.) or ((708/5 or 708/814).cds.) or ((73/1.45 or 73/1.65 or 73/1.65 or 73/767).cds.) or ((250/559.19 or 250/559.4).cds.)) and (data adj		
BRS	0	fusion)) and filter) and adaptive	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	49	(stationary adj sensor) and (scanning adj sensor)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS BRS	0	((US-4931982-\$).did.) and sensor ((US-4931982-\$).did.) and detector	USPAT USPAT	06/08/04 06/08/04
BRS	111	(700/129).ccis.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	0	((US-4931982-\$).did.) and sensor	USPAT	06/08/04
BRS	0	((US-4931982-\$).did.) and stationary	USPAT	
BRS	0			06/08/04
BRS	401	(((US-4931982-\$).did.) and output) and array	USPAT	06/08/04
	1954	array adj sensor	USPAT USPAT	06/08/04 06/08/04
	1954 0 4		USPAT	06/08/04
BRS BRS	0 4 4	array adj sensor (array adj sensor) and (data adj fusing) (array adj sensor) and (data same fusing) ((array adj sensor) and (data same fusing)) and sensor	USPAT USPAT USPAT USPAT USPAT	06/08/04 06/08/04 06/08/04 06/08/04 06/08/04
BRS BRS BRS	0 4 4 0	array adj sensor  (array adj sensor) and (data adj fusing)  (array adj sensor) and (data same fusing)  ((array adj sensor) and (data same fusing)) and sensor  ((((array adj sensor) and (data same fusing)) and scanning) and stationary	USPAT USPAT USPAT USPAT USPAT USPAT USPAT USPAT	06/08/04 06/08/04 06/08/04 06/08/04 06/08/04
BRS BRS BRS BRS	0 4 4 0	array adj sensor  (array adj sensor) and (data adj fusing)  (array adj sensor) and (data same fusing)  ((array adj sensor) and (data same fusing)) and sensor  ((((array adj sensor) and (data same fusing)) and scanning) and stationary  ((US-4931982-\$).did.) and frequency	USPAT	06/08/04 06/08/04 06/08/04 06/08/04 06/08/04
BRS BRS BRS	0 4 4 0	array adj sensor  (array adj sensor) and (data adj fusing)  (array adj sensor) and (data same fusing)  ((array adj sensor) and (data same fusing)) and sensor  ((((array adj sensor) and (data same fusing)) and scanning) and stationary	USPAT	06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04
BRS BRS BRS BRS BRS BRS	0 4 4 0 0 0 0	array adj sensor  (array adj sensor) and (data adj fusing)  (array adj sensor) and (data same fusing)  ((array adj sensor) and (data same fusing)) and sensor  ((((array adj sensor) and (data same fusing)) and sensor) and stationary  ((US-4931982-\$).did.) and frequency  ((US-4931982-\$).did.) and speed  ((US-4931982-\$).did.) and velocity  ((US-4931982-\$).did.) and odometer	USPAT	06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04
BRS BRS BRS BRS BRS BRS BRS BRS	0 4 4 0 0 0 0 0 0 0	array adj sensor  (array adj sensor) and (data adj fusing)  (array adj sensor) and (data same fusing)  ((array adj sensor) and (data same fusing)) and sensor  ((((array adj sensor) and (data same fusing)) and sensor) and stationary  (((US-4931982-\$).did.) and frequency  ((US-4931982-\$).did.) and speed  ((US-4931982-\$).did.) and velocity  ((US-4931982-\$).did.) and odorneter  odorneter	USPAT	06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04
BRS BRS BRS BRS BRS BRS BRS BRS	0 4 4 0 0 0 0 0 0 2366 106	array adj sensor  (array adj sensor) and (data adj fusing)  (array adj sensor) and (data same fusing)  ((array adj sensor) and (data same fusing)) and sensor  ((((array adj sensor) and (data same fusing)) and sensor)  (((((array adj sensor) and (data same fusing)) and sensor) and stationary  (((((((array adj sensor) and (data same fusing)) and sensor) and stationary  (((((((((((((((((((((((((((((((((((	USPAT	06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04
BRS BRS BRS BRS BRS BRS BRS BRS	0 4 4 0 0 0 0 0 0 0	array adj sensor  (array adj sensor) and (data adj fusing)  (array adj sensor) and (data same fusing)  ((array adj sensor) and (data same fusing)) and sensor  ((((array adj sensor) and (data same fusing)) and sensor) and stationary  (((US-4931982-\$).did.) and frequency  ((US-4931982-\$).did.) and speed  ((US-4931982-\$).did.) and velocity  ((US-4931982-\$).did.) and odorneter  odorneter	USPAT	06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04
BRS BRS BRS BRS BRS BRS BRS BRS BRS BRS	0 4 4 0 0 0 0 0 0 0 2366 106 43 42 37	array adj sensor  (array adj sensor) and (data adj fusing)  (array adj sensor) and (data same fusing)  ((array adj sensor) and (data same fusing)) and sensor  ((((array adj sensor) and (data same fusing)) and sensor)  ((((((array adj sensor) and (data same fusing)) and sensor) and scanning) and stationary  (((((((((((((((((((((((((((((((((((	USPAT	06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04
BRS BRS BRS BRS BRS BRS BRS BRS BRS BRS	0 4 4 0 0 0 0 0 0 2366 106 43 42 37 22	array adj sensor  (array adj sensor) and (data adj fusing)  (array adj sensor) and (data same fusing)  ((array adj sensor) and (data same fusing)) and sensor  ((((array adj sensor) and (data same fusing)) and sensor  (((((array adj sensor) and (data same fusing)) and sensor) and stationary  ((((((((u) - 4931982-\$), did.)) and frequency  (((((u) - 4931982-\$), did.)) and speed  ((((((u) - 4931982-\$), did.)) and velocity  ((((((u) - 4931982-\$), did.)) and dometer  odometer  odometer  odometer  (((((u) - 4931982-\$), did.)) and array)  (((((u) - 4931982-\$), did.)) and array)  (((((u) - 4931982-\$), did.)) and array) and sensors)  ((((((((u) - 4931982-\$), did.)))))))))))))))))))))))))))))))))))	USPAT	06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04
BRS	0 4 4 0 0 0 0 0 0 2366 106 43 42 37 22 0	array adj sensor  (array adj sensor) and (data same fusing)  (array adj sensor) and (data same fusing)  ((array adj sensor) and (data same fusing)) and sensor  ((((array adj sensor) and (data same fusing)) and sensor) and stationary  (((US-4931982-\$).did.) and sensor) and stationary  ((US-4931982-\$).did.) and speed  ((US-4931982-\$).did.) and velocity  ((US-4931982-\$).did.) and odometer  odometer  odometer  odometer and kalman adj filter  ((odometer and kalman adj filter) and array) and sensors  (((odometer and kalman adj filter) and array) and sensors) and cross same section)  (((((odometer and kalman adj filter) and array) and cross same section))  (((((((odometer and kalman adj filter) and array) and cross same section))	USPAT	06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04
BRS	0 4 4 0 0 0 0 0 0 2366 106 43 42 37 22	array adj sensor  (array adj sensor) and (data adj fusing)  (array adj sensor) and (data same fusing)  ((array adj sensor) and (data same fusing)) and sensor  (((array adj sensor) and (data same fusing)) and sensor  ((((array adj sensor) and (data same fusing)) and sensor) and stationary  ((((((array adj sensor) and (data same fusing)) and sensor) and stationary  (((((((((((((((((((((((((((((((((((	USPAT	06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04
BRS	0 4 4 0 0 0 0 0 2366 106 43 42 37 22 0	array adj sensor  (array adj sensor) and (data same fusing)  (array adj sensor) and (data same fusing)  ((array adj sensor) and (data same fusing)) and sensor  ((((array adj sensor) and (data same fusing)) and sensor) and stationary  (((US-4931982-\$).did.) and sensor) and stationary  ((US-4931982-\$).did.) and speed  ((US-4931982-\$).did.) and velocity  ((US-4931982-\$).did.) and odometer  odometer  odometer  odometer and kalman adj filter  ((odometer and kalman adj filter) and array) and sensors  (((odometer and kalman adj filter) and array) and sensors) and cross same section)  (((((odometer and kalman adj filter) and array) and cross same section))  (((((((odometer and kalman adj filter) and array) and cross same section))	USPAT	06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04
BRS	0 4 4 0 0 0 0 0 0 0 2366 106 43 42 37 22 0 411 0	array adj sensor (array adj sensor) and (data adj fusing) (array adj sensor) and (data same fusing) ((array adj sensor) and (data same fusing)) and sensor ((((array adj sensor) and (data same fusing)) and sensor) ((((((array adj sensor) and (data same fusing)) and sensor) and scanning) and stationary (((US-4931982-\$).did.) and frequency (((US-4931982-\$).did.) and speed (((US-4931982-\$).did.) and velocity (((US-4931982-\$).did.) and odorneter odorneter (((US-4931982-\$).did.) and odorneter (((US-4931982-\$).did.) and odorneter (((((US-4931982-\$).did.) and odorneter (((((((US-4931982-\$).did.) and odorneter) (((((((((US-4931982-\$).did.) and array)) and sensors) ((((((((((((((((((((((((((((((((((((	USPAT USPAT;	06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04
BRS	0 4 4 0 0 0 0 0 0 2366 106 43 42 37 22 0 411 0 1	array adj sensor  (array adj sensor) and (data adj fusing)  (array adj sensor) and (data same fusing)  ((array adj sensor) and (data same fusing)) and sensor  ((((array adj sensor) and (data same fusing)) and sensor  ((((((((array adj sensor) and (data same fusing))) and sensor) and stationary  (((((((((((((((((((((((((((((((((((	USPAT USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04
BRS	0 4 4 0 0 0 0 0 2366 106 43 42 37 22 0 411 0 1 1	array adj sensor (array adj sensor) and (data adj fusing) (array adj sensor) and (data same fusing) ((array adj sensor) and (data same fusing)) and sensor ((((array adj sensor) and (data same fusing)) and sensor) (((((array adj sensor) and (data same fusing)) and sensor) and stationary (((US-4931982-\$),did.) and sensor) and stationary ((US-4931982-\$),did.) and speed (((US-4931982-\$),did.) and velocity ((US-4931982-\$),did.) and odometer  odometer  odometer  odometer and kalman adj filter) (((odometer and kalman adj filter) and array) and sensors (((odometer and kalman adj filter) and array) and sensors) (((odometer and kalman adj filter) and array) and sensors) and cross ((((odometer and kalman adj filter) and array) and sensors) and cross ((((odometer and kalman adj filter) and array) and sensors) and cross same section) (((((((odometer and kalman adj filter) and array) and sensors) and cross same section) ((((((((((odometer and kalman adj filter) and array) and sensors) and cross same section) ((((((((((((((((((((((((((((((((((((	USPAT USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04
BRS	0 4 4 0 0 0 0 0 0 0 2366 106 43 42 37 22 0 411 0 1 1	array adj sensor  (array adj sensor) and (data adj fusing)  (array adj sensor) and (data same fusing)  ((array adj sensor) and (data same fusing)) and sensor  ((((array adj sensor) and (data same fusing)) and sensor  ((((((((array adj sensor) and (data same fusing))) and sensor) and stationary  (((((((((((((((((((((((((((((((((((	USPAT USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04 06/08/04
BRS	0 4 4 0 0 0 0 0 0 0 2366 106 43 42 37 22 0 411 0 1 1	array adj sensor) and (data adj fusing)  (array adj sensor) and (data same fusing)  ((array adj sensor) and (data same fusing)  ((array adj sensor) and (data same fusing)) and sensor  ((((array adj sensor) and (data same fusing)) and sensor  (((US-4931982-\$),did.) and frequency  ((US-4931982-\$),did.) and requency  ((US-4931982-\$),did.) and velocity  ((US-4931982-\$),did.) and velocity  ((US-4931982-\$),did.) and odometer  odometer  odometer  odometer and kalman adj filter  ((odometer and kalman adj filter) and array)  ((odometer and kalman adj filter) and array) and sensors) and cross  (((odometer and kalman adj filter) and array) and sensors) and cross  ((((odometer and kalman adj filter) and array) and sensors) and cross arme section)  (((((odometer and kalman adj filter) and array) and sensors) and cross arme section)  ((((((odometer and kalman adj filter) and array) and sensors) and cross arme section)  ((((((odometer and kalman adj filter) and array) and sensors) and cross arme section)  (((((((odometer and kalman adj filter) and array) and sensors) and cross arme section)  (((((((((((odometer and kalman adj filter) and array) and sensors) and cross arme section)  (((((((((((((((((((((((((((((((((((	USPAT USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04 06/08/04
BRS	0 4 4 0 0 0 0 0 0 2366 106 43 42 37 22 0 411 0 1 1 2 8	array adj sensor (array adj sensor) and (data adj fusing) (array adj sensor) and (data same fusing) ((array adj sensor) and (data same fusing)) and sensor ((((array adj sensor) and (data same fusing)) and sensor ((((((array adj sensor) and (data same fusing)) and sensor) (((((((((((array adj sensor) and (data same fusing)) and sensor) and stationary ((((((((((((((((((((((((((((((((((((	USPAT USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04 06/08/04
BRS	0 4 4 0 0 0 0 0 0 2366 106 43 42 37 22 0 411 0 1 1 2 8	array adj sensor) and (data adj fusing)  (array adj sensor) and (data same fusing)  ((array adj sensor) and (data same fusing)  ((array adj sensor) and (data same fusing)) and sensor  ((((array adj sensor) and (data same fusing)) and sensor  (((US-4931982-\$),did.) and frequency  ((US-4931982-\$),did.) and requency  ((US-4931982-\$),did.) and velocity  ((US-4931982-\$),did.) and velocity  ((US-4931982-\$),did.) and odometer  odometer  odometer  odometer and kalman adj filter  ((odometer and kalman adj filter) and array)  ((odometer and kalman adj filter) and array) and sensors) and cross  (((odometer and kalman adj filter) and array) and sensors) and cross  ((((odometer and kalman adj filter) and array) and sensors) and cross arme section)  (((((odometer and kalman adj filter) and array) and sensors) and cross arme section)  ((((((odometer and kalman adj filter) and array) and sensors) and cross arme section)  ((((((odometer and kalman adj filter) and array) and sensors) and cross arme section)  (((((((odometer and kalman adj filter) and array) and sensors) and cross arme section)  (((((((((((odometer and kalman adj filter) and array) and sensors) and cross arme section)  (((((((((((((((((((((((((((((((((((	USPAT USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04 06/08/04
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BRS	0 4 4 0 0 0 0 0 2366 106 43 42 37 22 0 411 0 1 1 2 2 8	(array adj sensor) and (data adj fusing) (array adj sensor) and (data same fusing) ((array adj sensor) and (data same fusing)) and sensor ((((array adj sensor) and (data same fusing)) and sensor (((((array adj sensor) and (data same fusing))) and sensor (((US-4931982-S),did.) and sensor)) and seanning) and stationary ((US-4931982-S),did.) and sensor) (((US-4931982-S),did.) and sensors ((((((us) despense))) (((((us) despense))) ((((((us) despense))) ((((((us) despense)))) (((((((us) despense)))) ((((((((us) despense))))) (((((((((us) despense)))))) (((((((((((((((((((((((((((((((	USPAT USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04 06/08/04
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